A Random Matrix Approach to Dynamic Factors in Macroeconomic Data

M. Snarska

Marian Smoluchowski Institute of Physics and Mark Kac Complex Systems Research Centre, Jagiellonian University
Reymonta 4, 30–059 Kraków, Poland

and

Cracow University of Economics, Department of Econometrics and Operations Research
Rakowicka 27, 31–510 Kraków, Poland

We show how random matrix theory can be applied to develop new algorithms to extract dynamic factors from macroeconomic time series. In particular, we consider a limit where the number of random variables \( N \) and the number of consecutive time measurements \( T \) are large but the ratio \( N/T \) is fixed. In this regime the underlying random matrices are asymptotically equivalent to Free Random Variables (FRV). Application of these methods for macroeconomic indicators for Poland economy is also presented.

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1. Introduction

Macroeconomic time series are characterized by two main features: comovements and cyclic phases of expansion and depression. Behind the econometric literature, especially on business cycle and VAR modeling there is an idea, that essential characteristics of macroeconomic time series are adequately captured by a small number of nearly independent factors.

On the other hand many empirical studies suggest to analyze many variables in order to understand the microeconomic mechanisms behind the fluctuations, where both \( N \)- the number of variables and \( T \) the length of a time series are typically large, and typically of the same order. Surprisingly most of the models developed in this field of science can precisely describe only static properties of the correlation structure. There is a strong need for models and algorithms, that can accurately capture the above described features of macroeconomic time series, are dynamic and allow for a richer spatio–temporal structure.

In this paper we present new algorithms, based on Random Matrix Theory that countenance extracting potentially useful factors in macroeconomic time series. In the first section we uncover external temporal correlation structure, using the assumption that the characteristic of each individual time series is meticulously depicted by the \( \text{VARMA}(q_1,q_2) \) structure with the same parameters. The second method encompasses exposition of internal correlation structure between two different sets of variables, after the external correlations are properly reduced.

2. Unraveling lagged external temporal correlations from \( \text{VARMA}(p,q) \)

Finite order vector autoregressive moving average models (VARMA) motivated by Wold decomposition theorem [1] as an appropriate multivariate setting for studying the dynamics of stationary time series. Vector autoregressive (VAR) models are cornerstones in contemporary macroeconomics, being a part of an approach called the “dynamic stochastic general equilibrium” (DSGE), which is superseding traditional large-scale macroeconomic forecasting methodologies [2]. The motivation behind them is based on the assertion that more recent values of a variable are more likely to contain useful information about its future movements than the older ones. On the other hand, a standard tool in multivariate time series analysis is vector moving average (VMA) models, which is really a linear regression of the present value of the time series w.r.t. the past values of a white noise. A broader class of stochastic processes used in macroeconomics comprises both these kinds together in the form of vector autoregressive moving average (VARMA) models. These methodologies can capture certain spatial and temporal structures of multi-dimensional variables which are often neglected in practice; including them not only results in more accurate estimation, but also leads to models which are more interpretable.

2.1. Correlated Gaussian random variables

We will consider a situation of \( N \) time–dependent random variables which are measured at \( T \) consecutive time moments (separated by some time interval \( \delta t \)); let \( Y_{ia} \) be the value of the \( i \)-th \( (i = 1, \ldots, N) \) random number at the \( a \)-th time moment \( (a = 1, \ldots, T) \); together, they...
make up a rectangular $N \times T$ matrix $Y$. Firstly we will assume, each $Y_{ia}$ is supposed to be drawn from a Gaussian probability distribution, and that they have mean values zero, $(Y_{ia}) = 0$. A set of correlated zero-mean Gaussian numbers is fully characterized by the two-point covariance function, $c_{ia,jb} \equiv (Y_{ia} Y_{jb})$ if the underlying stochastic process generating these numbers is stationary. The stationarity condition for VARMA($q_1,q_2$) stochastic processes implies certain restrictions on their parameters; for details, we refer to [3]. We will restrict our attention to an even narrower class where the cross-covariances between different variables and the auto-covariances between different time moments are factorized, i.e.,

$$ (Y_{ia} Y_{jb}) = c_{ij} A_{ab}. \quad (1) $$

2.1.1 Estimating external cross-covariances

The realized cross-covariance between degrees $i$ and $j$ at the same time $a$ is $Y_{ia} Y_{ja}$, the simplest method to estimate the today’s cross-covariance $c_{ij}$ is to compute the time average (named “Pearson estimator”),

$$ c_{ij} \equiv \frac{1}{T} \sum_{a=1}^{T} Y_{ia} Y_{ja}, \text{ i.e.}, $$

$$ c = \frac{1}{T} \sum_{a=1}^{T} Y Y^T = \frac{1}{T} \sqrt{C Y A Y^T} \sqrt{C}. \quad (2) $$

The random matrix $c$ is called a “doubly correlated Wishart ensemble” [4]. It is obvious, that our estimator will reflect the true covariances only to a certain degree, with a superimposed broadening due to the finiteness of the time series i.e., estimation accuracy will depend on the “rectangularity ratio,” $r \equiv \frac{N}{T}$: the closer $r$ to zero, the more truthful the estimate. Furthermore we will consider the situation, where

$$ N \to \infty, \quad T \to \infty, \quad \text{such that} \quad r = \text{fixed}. \quad (3) $$

2.2. Free random variables calculus crash course

2.2.1. $M$-transform and the spectral density

Let’s consider (real symmetric $K \times K$) random matrix $H$. The average of its eigenvalues $\lambda_1, \ldots, \lambda_K$ is concisely encoded in the “mean spectral density,”

$$ \rho_H(\lambda) \equiv \frac{1}{K} \sum_{i=1}^{K} \delta(\lambda - \lambda_i) = \frac{1}{K} \langle \text{Tr}(M_{1K} - H) \rangle. \quad (4) $$

On the practical side, it is more convenient to work with either of the two equivalent objects,

$$ G_H(z) \equiv \frac{1}{K} \left( \text{Tr} \frac{1}{z 1_{K} - H} \right), \text{ or} $$

$$ M_H(z) \equiv z G_H(z)^{-1} - 1, \quad (5) $$

referred to as the “Green’s function” (or the “resolvent”) and the “$M$-transform” of $H$ (“moments generating function,”). The latter one serves better in the case of multiplication of random matrices.

2.2.2. The $N$-transform and free random variables

The doubly correlated Wishart ensemble $c$ (2) may be viewed as a product of several random and non-random matrices. The general problem of multiplying random variables in classical probability theory can be effectively handled in the special situation when the random terms are independent: then, the exponential map reduces it to the addition problem of independent random numbers, solved by considering the logarithm of the characteristic functions of the respective PDFs, which proves to be additive. In matrix probability theory due to D. Voiculescu and coworkers and R. Speicher [5–6], we have a parallel commutative construction in the noncommutative world (c.f. table 1). It starts with the notion of “freeness,” which basically comprises probabilistic independence together with a lack of any directional correlation between two random matrices. This nontrivial new property happens to be the right extension of classical independence, as it allows for an efficient algorithm of multiplying free random variables (FRV), which we state below:

**Step 1:** Suppose we have two random matrices, $H_1$ and $H_2$, mutually free. Their spectral properties are best wrought into the $M$–transforms (5), $M_{H_1}(z)$ and $M_{H_2}(z)$.

**Step 2:** The critical maneuver is to turn attention to the functional inverses of these $M$–transforms, the so-called “$N$–transforms,”

$$ M_H(N_H(z)) = M_H(M_H(z)) = z \quad (6) $$

**Step 3:** The $N$–transforms submit to a very straightforward rule upon multiplying free random matrices (the “FRV multiplication law”), for free $H_1$, $H_2$,

$$ N_{H_1 H_2}(z) = \frac{z}{1 + z} N_{H_1}(z) N_{H_2}(z), \quad (7) $$

**Step 4:** Finally, it remains to functionally invert the resulting $N$–transform $N_{H_1H_2}(z)$ to gain the $M$–transform of the product, $M_{H_1H_2}(z)$.

2.2.3. Extracting external correlations

The innate potential of the FRV multiplication algorithm (7) is surely revealed when inspecting the doubly correlated Wishart random matrix $c = (1/T) \sqrt{C Y A Y^T} \sqrt{C}$ (2). This has been done in detail in [7–8], so we will only accentuate the main results here, referring the reader to the original papers for an exact explanation. The idea is that one uses twice the cyclic property of the trace (which permits cyclic shifts in the order of the terms), and twice the FRV multiplication law (7) (to break the $N$–transforms of products of matrices down to their constituents), in order to reduce the problem to solving the uncorrelated Wishart ensemble $(1/T) \tilde{Y}^T \tilde{Y}$. This last model is further simplified, again by the cyclic property and the FRV multiplication rule applied once, to the standard GOE random matrix squared (and the projector $P \equiv \text{diag}(1_N, 0_T - N)$, designed to chip the rectangle $\tilde{Y}$ off the square GOE), whose properties are firmly established. Let us sketch the derivation,

$$ N_c(z) \overset{cyclic}{=} N \frac{z}{1 + z} \tilde{Y} A^T C(z) $$

$$ r_{\text{FRV}} \overset{cyclic}{=} \frac{z}{1 + z} N \frac{z}{1 + z} \tilde{Y} A^T C(z) $$

$$ \overset{cyclic}{=} \frac{z}{1 + z} N \frac{z}{1 + z} \tilde{Y} A^T C(z) \overset{cyclic}{=} \frac{z}{1 + z} \frac{z}{1 + z} \tilde{Y} A^T C(z) $$
\[ z = \frac{z}{1 + z} N_T Y_T N_C(z) \]

This is the basic formula. Since the spectral properties of \( c \) are given by its \( M \)-transform, \( M \equiv M_c(z) \), it is more pedagogical to recast (8) as an equation for the unknown \( M \),

\[ z = r M N_T(r M) N_C(M). \]

(9)

It provides a means for computing the mean spectral density of a doubly correlated Wishart random matrix once the “true” covariance matrices \( C \) and \( A \) are given.

In this communication, only a particular instance of this fundamental formula is applied, namely with an arbitrary auto–covariance matrix \( A \), but with trivial cross-

Parallel between classical and noncommutative probability.

<table>
<thead>
<tr>
<th>Classical Probability</th>
<th>Noncommutative probability (FRV)</th>
</tr>
</thead>
<tbody>
<tr>
<td>( x ) — random variable, ( p(x) ) — pdf</td>
<td>( H ) — random matrix, ( P(H) ) — spectral density ( g(\lambda) d\lambda )</td>
</tr>
<tr>
<td>characteristic function ( g_s(z) \equiv \langle e^{i z x} \rangle )</td>
<td>Green’s function ( G_H(z) = \frac{1}{N} \langle \text{Tr} \frac{1}{1 - H z} \rangle ) or ( M )-transform ( M(z) = z G_H(z) - 1 )</td>
</tr>
<tr>
<td>independence</td>
<td>freeness</td>
</tr>
<tr>
<td>addition of independent r.v.:</td>
<td>addition of f.r.v.</td>
</tr>
<tr>
<td>the logarithm of the characteristic function,</td>
<td>the Blue’s function</td>
</tr>
<tr>
<td>( r_s(z) \equiv \log g_s(z) ), is additive,</td>
<td>( G_H(B_H(z)) = B_H(G_H(z)) = z ), is additive,</td>
</tr>
<tr>
<td>( r_s(z) + r_s(z) = r_s(z) + r_s(z) )</td>
<td>( B_{H_1 + H_2}(z) = B_{H_1}(z) + B_{H_2}(z) - \frac{1}{z} )</td>
</tr>
<tr>
<td>multiplication of independent r.v.:</td>
<td>multiplication of free r.v.:</td>
</tr>
<tr>
<td>reduced to the addition problem</td>
<td>the ( N )-transform,</td>
</tr>
<tr>
<td>via the exponential map, owing to</td>
<td>( M_H(N_H(z)) = N_H(M_H(z)) = z ), is multiplicative</td>
</tr>
<tr>
<td>( e^{z_1} e^{z_2} = e^{z_1 + z_2} )</td>
<td>( N_{H_1, H_2}(z) = \frac{1}{1 + z} N_{H_1}(z) N_{H_2}(z) )</td>
</tr>
</tbody>
</table>

2.3. The VARMA\((q_1, q_2)\) process

2.3.1. The Definition of VARMA\((q_1, q_2)\)

One can define stochastic processes called VARMA\((q_1, q_2)\) in the following way as a convolution of VAR\((q)\) and VMA\((q)\) processes:

\[ Y_{ia} - \sum_{\beta=1}^{q_1} b_\beta Y_{i,a-\beta} = \sum_{\alpha=0}^{q_2} a_\alpha \epsilon_{i,a-\alpha}. \]

(11)

To be more specific, we consider a situation when \( N \) stochastic variables evolve according to identical independent VARMA\((q_1, q_2)\) (vector autoregressive moving average processes), which we sample over a time span of \( T \) moments.

VMA\((q)\) (vector moving average) process is a simple generalization of the standard univariate weak–stationary moving average MA\((q)\). In such a setting, the value \( Y_{ia} \) of the \( i \)-th \( (i = 1, \ldots, N) \) random variable at time moment \( a \) \( (a = 1, \ldots, T) \) can be expressed as

\[ Y_{ia} = \sum_{\alpha=0}^{q} a_\alpha \epsilon_{i,a-\alpha}. \]

(12)

Here all the \( \epsilon_{ia} \)'s are IID standard (mean zero, variance one) Gaussian random numbers (white noise), \( \langle \epsilon_{ia} \epsilon_{ja} \rangle = \delta_{ij} \delta_{ab} \). The \( a_\alpha \)'s are some \((q + 1)\) real constants; importantly, they do not depend on the index \( i \), which reflects the fact that the processes are identical and independent (no “spatial” covariances among the variables). The rank \( q \) of the process is a positive integer.

The VAR\((q)\) (vector auto–regressive) processes part is somewhat akin to (12), i.e., we consider \( N \) decoupled copies of a standard univariate AR\((q)\) process,

\[ Y_{ia} - \sum_{\beta=1}^{q} b_\beta Y_{i,a-\beta} = a_0 \epsilon_{ia}. \]

(13)

It is again described by the demeaned and standardized Gaussian white noise \( \epsilon_{ia} \) (which triggers the stochastic evolution), as well as \((q + 1)\) real constants \( a_0, b_\beta \), with \( \beta = 1, \ldots, q \). As announced before, the time stretches to the past infinity, so no initial condition is necessary. Although at first sight (13) may appear to be a more involved recurrence relation for the \( Y_{ia} \)'s, it is actually easily reduced to the VMA\((q)\) case: It remains to remark that if one exchanges the \( Y_{ia} \)'s with the \( \epsilon_{ia} \)'s, one precisely arrives at the VMA\((q)\) process with the constants \( a_0^2 \equiv 1/a_0, a_\beta^2 \equiv -b_\beta/a_0, \beta = 1, \ldots, q \). In other words, the auto–covariance matrix \( A^{(s)} \) of the VAR\((q)\) process

\[ r_M = M_A \left( \frac{z}{r(1 + M)} \right), \]

(10)

which will be strongly exploited below.

For all this, we must in particular take both \( N \) and \( T \) large from the start, with their ratio \( r \equiv N/T \) fixed (3). More precisely, we stretch the range of the \( a \)-index from minus to plus infinity. This means that all the finite–size effects (appearing at the ends of the time series) are readily disregarded. In particular, there is no need to care about initial conditions for the processes, and all the recurrence relations are assumed to continue to the infinite past.

TABLE I
(13) is simply the inverse of the auto–covariance matrix $A^{(2)}$ of the corresponding VMA($q$) process with the described modification of the parameters,

$$A^{(3)} = \left( A^{(2)} \right)^{-1}.$$ 

This inverse exists thanks to the weak stationarity supposition.

The auto–covariance matrix $A^{(5)}$ of this process is simply the product (in any order) of the auto–covariance matrices of the VAR and VMA pieces; more precisely,

$$A^{(5)} = \left( A^{(4)} \right)^{-1} A^{(1)} \tag{14}$$

where $A^{(1)}$ corresponds to the generic VMA($q_2$) model, while $A^{(4)}$ denotes the auto–covariance matrix of VMA($q_1$) with a slightly different modification of the parameters compared to the previously used, namely $a_{0}^{(4)} \equiv 1$, $a_{\beta}^{(4)} \equiv -b_{\beta}$, for $\beta = 1, \ldots, q_1$.

The $M$–transform of $A^{(5)}$ can consequently be derived from the general formulas [8]. We will evaluate here the pertinent integral only for the simplest VARMA(1,1) process, even though an arbitrary case may be handled by the technique of residues,

$$M_{A^{(5)}}(z) = \frac{1}{a_0 a_1 + b_1 z} : \left( -a_0 a_1 + \frac{z \left( a_0 a_1 + (a_0^2 + a_1^2) b_1 + a_0 a_1 b_1^2 \right) \sqrt{(1 - b_1)^2 z - (a_0 + a_1)^2 \sqrt{(1 + b_1)^2 z - (a_0 - a_1)^2)}}{(1 - b_1)^2 z - (a_0 + a_1)^2 \sqrt{(1 + b_1)^2 z - (a_0 - a_1)^2}} \right) \tag{15}$$

2.4. Example from macroeconomic data

We apply the method described above to Polish macroeconomic data. The motivation behind is twofold. First of all economic theory rarely has any sharp implications about the short-run dynamics of economic variables (so called scarcity of economic time series). Secondly in these very rare situations, where theoretical models include a dynamic adjustment equation, one has to work hard to exclude the moving average terms from appearing in the implied dynamics of the variables of interest.

2.4.1. An application to macroeconomic data

Let us pursue further the above analysis of the VARMA(1,1) model on a concrete example of real data. Economists naturally think of co–movement in economic time series as arising largely from relatively few key economic factors like productivity, monetary policy and so forth. Classical way of representing this notion is in terms of statistical factor model, for which we allow the limited spatio–temporal dependence expressed via our VARMA(1,1) model. Two empirical questions are addressed in this section:

1. How the empirical data behave? Does the eigenvalues represent similar structural to financial market data? In other words, does the macroeconomic data represent collective response to the shock expressed in term of VARMA(1,1) model or are there any apparent outliers.

2. Should then the forecasts be constructed using small factor models or are there any non–zero, but perhaps small coefficients. If so, then the large scale model framework is appropriate.

We investigate $N = 52$ various macroeconomic time series for Poland of length $T = 118$. They have been selected on a monthly basis in such a manner so as to cover most of the main sectors of the Polish economy, i.e., the money market, domestic and foreign trade, labor market, balance of payments, inflation in different sectors, etc. The time series were taken directly from the Reuters©3000Xtra database. Although longer time series for Poland are accessible, we restrict ourselves to the last ten years in order to avoid the effects of structural change. We assume that each economic variable is affected by the same shock (i.e., the “global market shock”) of an ARMA(1,1) type with unknown parameters, which we are to estimate; the AR part implies that the shock dies quite quickly, while the MA part is responsible for the persistency of the shock. To preserve the proper VARMA representation, the original time series were transformed using one of the following methods:

- First, many of the series are seasonally adjusted by the reporting agency.
- Second, the data were transformed to eliminate trends and obvious nonstationarities. For real variables, this typically involved transformation to growth rates (the first difference of logarithms), and for prices this involved transformation to changes in growth rates (the second difference of logarithms).
- Interest rates were transformed to first differences.
- Finally, some of the series contained a few large outliers associated with events like labor disputes, other extreme events, or with data problems of various sorts. These outliers were identified as observations that differed from the sample median by more than 6 times the sample interquartile range, and these observations were dropped from the analysis.

In fig.1 we plot these time series (LEFT), and we make (RIGHT) a histogram of the mean spectral density $\rho_{c}(\lambda)$, which we compare to a theoretical prediction solving the FVR equation for (15) with the estimated values of the parameters $a_0, a_1, b_1$. We have also plotted the standard Marčenko–Pastur (Bai-Silverstein) [9–10].

2.4.2. Discussion

The result is important for forecast design, but more importantly, it provides information about the way macroeconomic variable interact. The empirical data as compared to the spectral density equation suggest that a lot of eigenvalues, similarly to stock market data express marginal predictive content. One can suppose, that each of the economic time series contains important information about the collective movements, that cannot be
gleaned from other time series. Alternatively, if we suppose that macro variables interact in the simplest low-dimensional way suggested by VARMA(1,1) model, the conformity is nearly ideal (modulo the finite-size effects at the right edge of the spectrum). The economic time series express common response to the "global shock" process i.e., each eigenvalue now contains useful information about the values of the factors, that affect co-movement and hence useful information about the future behavior of economy. Thus, while many more eigenvalues appear to be useful, the predictive component is apparently common to many series in a way suggested by our simplified VARMA(1,1) model. The above analysis on a real complex systems example - i.e. Economy of Poland, for which we have assumed, that each of the time series under study is generated by the same type of uni- and thus us the "Wishart-fit" (purple line).

3. Unraveling internal temporal correlations via SVD technique

In order to investigate the temporal properties of the internal correlations between two data sets one is often interested not only in the analysis of its static properties given by Pearson estimator (2), $C_X = \frac{1}{T} XX^T$ but more likely how this features behave over a certain period of time. Again the primary way to describe cross-correlations in a Gaussian framework is through the two-point covariance function (1),

$$C_\text{ia, jb} \equiv \langle X_\text{ia} X_\text{jb} \rangle,$$

where $X_\text{ia} \equiv x_\text{ia} - \langle x_\text{ia} \rangle$ are mean adjusted data, that can be further collected into a rectangular $N \times T$ matrix $R$. The average $\langle \ldots \rangle$ is understood as taken according to some probability distribution whose functional shape is stable over time, but whose parameters may be time-dependent. In previous sections we have used a very simplified form of the two-point covariance function (1), namely with cross-covariances and auto-covariances factorized and non-random,

$$C_\text{ia, jb} = C_{ij} A_{ab}.$$

We have assembled coefficients into an $N \times N$ cross-covariance matrix $C$ and a $T \times T$ auto-covariance matrix $A$: both are taken symmetric and positive-definite. The matrix of “temporal structure” $A$ is a way to model two temporal effects: the (weak, short-memory) lagged correlations between the returns, as well as the (stronger, long-memory) lagged correlations between the volatilities (weighting schemes, eg.EWMA[11]). On the other hand, the matrix of spatial correlations $C$ models the hidden factors affecting the variables, thereby reflecting the structure of mutual dependencies of the complex system. The salient feature assumed so far, these two matrices were decoupled and the assumption about the Gaussianity of random variables provides crude approximation, that variances of all random variables always exist. This was sufficient to fully characterize the dependencies of the $X_\text{ia}$’s. However, in more realistic circumstances (i.e., building efficient multivariate models, which help understanding the relation between a large number of possible causes and resulting effects) one is more interested in the situations, where the spatio-temporal structure does not factorize. Cross-correlations technique (sometimes alluded as "time-lagged correlations technique") is most likely meets these critical requirements.

$$C_\text{ia, ja+}\Delta(\Delta) = \frac{1}{T} \sum_{a=1}^{T} X_\text{ia} X_{\text{ja+}\Delta}, \quad (16)$$

The precise answer boils down to how to separate the spectrum of such a covariance matrix in the large $N$, large $T$ limit (i.e., thermodynamical limit), when one can make use of the power of FRV calculus (see [12]) for a solution based on the circular symmetry of the problem and Gaussian approximation). In this chapter we will very closely follow the method presented in [13], where the authors suggested to compare the singular value spec-
3.1. Mathematical formulation of a problem

Due to the works [2,16–17] it is believed that, the system itself should determine the number of relevant input and output factors. In the simplest approach one would take all the possible input and output factors and systematically correlate them, hoping to unravel the hidden structure. This procedure swiftly blow up with just few variables. The cross-equation correlation matrix contains all the information about contemporaneous correlation in a Vector model and may be its greatest strength and its greatest asset. Since no questionable a priori assumptions are imposed, fitting a Vector model allows one to systematically correlate them, hoping to unravel the hidden structure. For pedagogical purposes we rederive all these results in the language of FRV presented in the table I. Furthermore we extend the results obtained in [15] to meet encounter time-lagged correlations.

3.1.1. Basic framework and notation

We will divide all variables into two subsets i.e., focus on $N$ input factors $X_a$ ($a = 1, \ldots, N$) and $M$ output factors $Y_\alpha$ ($\alpha = 1, \ldots, M$) with the total number of observations being $T$. All time series are standardized to have zero mean and unit variance. The data can be completely different or be the same variables but observed at different times. First one has to remove potential correlations inside each subset, otherwise it may interfere with the out-of-sample signal. To remove the correlations inside each sample we form two correlation matrices, which contain information about in-the-sample correlations.

\[
\mathbf{C}_X = \frac{1}{T} \mathbf{X} \mathbf{X}^T \quad \mathbf{C}_Y = \frac{1}{T} \mathbf{Y} \mathbf{Y}^T
\]  

(17)

The matrices are then diagonalized, provided $T > N$, $M$, and the empirical spectrum is compared to the theoretical Marčenko–Pastur spectrum [10, 36–28] in order to unravel statistically significant factors. The eigenvalues, which lie much below the lower edge of the Marčenko–Pastur spectrum represent the redundant factors, rejected by the system, so one can exclude them from further study and in this manner reduce somewhat the dimensionality of the problem, by removing possibly spurious correlations. Having found all eigenvectors and eigenvalues, one can then construct a set of uncorrelated unit variance input variables $\hat{X}$ and output variables $\hat{Y}$.

\[
\hat{X}_{at} = \frac{1}{\sqrt{T \lambda_a}} Y^T X_t \quad \hat{Y}_{\alpha t} = \frac{1}{\sqrt{T \lambda_\alpha}} U^T Y_t,
\]  

(18)

where $V, U$, $\lambda_a$, $\lambda_\alpha$ are the corresponding eigenvectors and eigenvalues of $C_X$, $C_Y$ respectively. It is obvious, that $\hat{C}_X = \hat{X} \hat{X}^T$ and $\hat{C}_Y = \hat{Y} \hat{Y}^T$ are identity matrices, of dimension, respectively, $N$ and $M$. Using general property of diagonalization, this means that the $T \times T$ matrices $D_{\hat{X}} = \hat{X} \hat{X}^T$ and $D_{\hat{Y}} = \hat{Y} \hat{Y}^T$ have exactly $N$ (resp. $M$) eigenvalues equal to 1 and $T-N$ (resp. $T-M$) equal to zero. These non-zero eigenvalues are randomly arranged on a diagonal. Finally we can reproduce the asymmetric $M \times N$ cross-correlation matrix $G$ between the $\hat{Y}$ and $\hat{X}$:

\[
G = \hat{Y} \hat{X}^T,
\]

which includes only the correlations between input and output factors. In general the spectrum of such a matrix is complex, but we will use the singular value decomposition (SVD) technique (c.f. [29]) to find the empirical spectrum of eigenvalues.

3.1.2. The singular value decomposition

The singular value spectrum represent the strength of cross-correlations between input and output factors. Suppose $G$ is an $M \times N$ matrix whose entries are either real or complex numbers. Then there exists a factorization of the form

\[
G = U \Sigma V^T,
\]

where $U$ is an $M \times M$ unitary matrix. The columns of $U$ form a set of orthonormal "output" basis vector directions for $G$ - these are the eigenvectors of $G^T G$. $\Sigma$ is $M \times N$ diagonal matrix with nonnegative real numbers on the diagonal, which can be thought of as scalar "gain controls" by which each corresponding input is multiplied to give a corresponding output. These are the square roots of the eigenvalues of $G^T G$ and $G G^T$ that correspond with the same columns in $U$ and $V$. $V^T$ denotes the conjugate transpose of $V$, an $N \times N$ unitary matrix, whose columns form a set of orthonormal "input" or vector directions for $G$. These are the eigenvectors of $G G^T$. A common convention for the SVD decomposition is to order the diagonal entries $\Sigma_{\alpha \beta}$ in descending order. In this case, the diagonal matrix $\Sigma$ is uniquely determined by $G$ (though the matrices $U$ and $V$ are not). The diagonal entries of $\Sigma$ are known as the singular values of $G$.

3.2. Singular values from free random matrix theory

In order to evaluate these singular eigenvalues, assume without loss of generality $M < N$. The trick is to consider the matrix $M \times M$ matrix $G G^T$ (or the $N \times N$ matrix $G^T G$ if $M > N$), which is symmetrical and has $M$ positive eigenvalues, each of which being equal to the square of a singular value of $G$ itself. Furthermore use
the cyclic properties of the trace. Then non-zero eigenvalues of 
\[ GG^T = \hat{Y} \hat{X}^T \hat{X} \hat{Y}^T \]
are then the same (up to the zero modes) as those of the 
\[ T \times T \]
matrix 
\[ D = D_\hat{X} D_\hat{Y} = \hat{X}^T \hat{X} \hat{Y}^T \hat{Y} \]
on the FRV algorithm for cross-correlation matrix.

From this, one easily obtains:
\[ N_{D_X}(z) \left( \frac{m}{N_{D_X}(z)} + \frac{1 - m}{N_{D_Y}(z)} \right) - 1 = z \]
\[ N_{D_X}(z) = \frac{m + z}{z} \quad N_{D_Y}(z) = \frac{n + z}{z} \]
and one readily gets the \( N \)-transform for the matrix
\[ D_\hat{X} \cdot D_\hat{Y} \]
\[ N_{D_X \cdot D_Y}(z) = \frac{(m + z)(n + z)}{z^2} \]
Inverting functionally (20)
\[ N_{D_X \cdot D_Y}(z) G_D (N_{D_X \cdot D_Y}(z)) = z + 1 \]
i.e., solving the second order equation in \( z \), one is able to find the Green’s function of a product \( D_\hat{X} \cdot D_\hat{Y} \)
\[ G(N(z)) = \left[ 2 - (n + m + N(z)) \right] \]

Factors affecting the set of output variables for lagged spectra.

<table>
<thead>
<tr>
<th>( Y )</th>
<th>( X )</th>
<th>Type of correlation</th>
</tr>
</thead>
<tbody>
<tr>
<td>CPI in communication sector</td>
<td>completed dwellings</td>
<td>negative</td>
</tr>
<tr>
<td>CPI in clothing sector</td>
<td>net balance of payments of goods</td>
<td>negative</td>
</tr>
<tr>
<td>CPI in restaurants and hotels sector</td>
<td>direct investments</td>
<td>positive</td>
</tr>
<tr>
<td>CPI in transport sector</td>
<td>employment in enterprise sector</td>
<td>positive</td>
</tr>
<tr>
<td>CPI in communication sector</td>
<td>employment in manufacturing sector</td>
<td>positive</td>
</tr>
<tr>
<td>CPI in clothing sector</td>
<td>foreign exchange reserves</td>
<td>negative</td>
</tr>
<tr>
<td>CPI in restaurants and hotels sector</td>
<td>foreign exchange reserves</td>
<td>negative</td>
</tr>
<tr>
<td>CPI in transport sector</td>
<td>total export</td>
<td>negative</td>
</tr>
</tbody>
</table>

3.2.1. FRV algorithm for cross-correlation matrix

As usual we will start with constructing the Green’s function for matrices \( D_\hat{X} \) and \( D_\hat{Y} \). Each of these matrices, have off-diagonal elements equal to zero, while on diagonal a set of \( M \) (or \( N \) respectively) randomly distributed eigenvalues equal to 1

\[ G_{D_X} = \frac{1}{T} \left( \frac{M}{z - 1} + \frac{T - M}{z} \right) = \frac{m}{z - 1} + \frac{1 - m}{z} \]
\[ m = \frac{M}{T} ; \]
\[ G_{D_Y} = \frac{1}{T} \left( \frac{N}{z - 1} + \frac{T - N}{z} \right) = \frac{n}{z - 1} + \frac{1 - n}{z} \]
\[ n = \frac{N}{T} . \]

Then:
\[ S_{D_X \cdot D_Y}(z) = S_{D_X}(z) \cdot S_{D_Y}(z) \]
or equivalently
\[ \frac{1 + z}{z} N_{D_X \cdot D_Y}(z) = N_{D_X}(z) \cdot N_{D_Y}(z) \]
where:
\[ S_X(z) = \frac{1 + z}{z} \chi_X(z) \quad N_X(z) = \frac{1}{\chi_X(z)} \]
\[ N_X(z) G(N_X(z)) - 1 = z \]
\[-\sqrt{(n+m-N(z))^2-4(1-N(z))mn}/2N(z)(1-N(z))\]
where we have omitted the subscripts for brevity. Subsequently mean spectral density is obtained from the standard relation
\[
\lim_{\epsilon \to 0^+} \frac{1}{\lambda + i\epsilon} = PV\left(\frac{1}{\lambda}\right) - i\pi\delta(\lambda)
\]
\[
\Rightarrow \rho_{\text{D}}(\lambda) = -\frac{1}{\pi}\text{Im}\text{G}_{\text{D}}(\lambda + i\epsilon).
\]
The final result i.e., the benchmark case where all (standardized) variables \(X\) and \(Y\) are uncorrelated, meaning that the ensemble average \(E(C_X) = E(XX^T)\) and \(E(C_Y) = E(YY^T)\) are equal to the unit matrix, whereas the ensemble average cross-correlation \(E(G) = E(YX^T)\) is identically zero, reads as in original paper [13]:
\[
\rho_{\text{D}}(\lambda) = \max(1-n,1-m)\delta(\lambda) + 
+ \max(m+n-1,0)\delta(\lambda-1) + 
+ \frac{\text{Re}(\sqrt{\lambda^2-s_-})(\lambda_+ - s_-)}{\pi(1-\lambda^2)}
\]
where \(s_\pm = n+m - 2mn \pm 2\sqrt{mn(1-n)(1-m)}\) are the two positive roots of the quadratic expression under the square root.

\[
\rho_{\text{D}}(\lambda) = \max(1-n,1-m)\delta(\lambda) + 
+ \max(m+n-1,0)\delta(\lambda-1) + 
+ \frac{\text{Re}(\sqrt{\lambda^2-s_-})(\lambda_+ - s_-)}{\pi(1-\lambda^2)}
\]
where \(s_\pm = n+m - 2mn \pm 2\sqrt{mn(1-n)(1-m)}\) are the two positive roots of the quadratic expression under the square root.

It is easy to discover the fact, that in the limit \(T \to \infty\) at fixed \(N, M\), all singular values collapse to zero, as they should since there is no true correlations between \(X\) and \(Y\); the allowed band in the limit \(n, m \to 0\) becomes:
\[
\lambda \in \left[\sqrt{m} - \sqrt{n}, \sqrt{m} + \sqrt{n}\right].
\]
When \(n \to m\), the support becomes \(\lambda \in [0, 2\sqrt{m(1-m)}]\) (plus a \(\delta\) function at \(\lambda = 1\) when \(n + m > 1\)), while when \(m = 1\), the whole band collapses to a \(\delta\) function at \(\lambda = \sqrt{1-n}\). For \(n + m \to 1^+\) there is an initial singularity of \(\rho(\lambda)\) \(\lambda = 1\) diverging as \((1-\lambda)^{-1/2}\). Ultimately \(m \to 0\) at fixed \(n\), one finds that the whole band collapses again to a \(\delta\) function at \(\lambda = \sqrt{n}\).

### 3.2. SVD cleaning technique and the MP² case
The results from the previous section were obtained under belief there were no correlations between input and output samples of infinite sizes. However, for a given finite size sample, the eigenvalues of \(C_X\) and \(C_Y\) will differ from unit, and the singular values of \(G\) will not be zero and instead cross-correlations between input and output variables are involved. The SVD spectrum in that case is the convolution of two Marcenko–Pastur [10] distributions with parameters \(m\) and \(n\), respectively, which reads, for \(r = m, n < 1:\)
\[
\rho_{\text{MP}}(\lambda) = \frac{1}{2\pi\beta\lambda} \text{Re}(\sqrt{\lambda - \lambda_-})(\lambda_+ - \lambda)
\]
with \(\lambda_\pm = (1 \pm \sqrt{\lambda})\). The \(N\)-transform of this density takes a particularly simple form (cf. [7] for an exact derivation)
\[
\mathbf{N}_{\text{MP}}(z) = \frac{1 + z}{1 + rz}
\]
where \(\lambda_\pm = (1 \pm \sqrt{\lambda})\). The singular values of \(G\) are obtained as the square-root of the eigenvalues of \(D = X^TY^TY\) and under assumption, that \(X^TX\) and \(Y^TY\) are mutually free, after having noted that the \(N\)-transform of the \(T\times T\) matrices \(X^TX\) and \(Y^TY\) are now given by:
\[
\mathbf{N}(z) = \frac{(1+z)(1+rz)}{r^2z}
\]
one can again use the multiplication rule of \(N\)-transforms and finds the Green’s function of \(D\) by solving the following cubic equation for \(z:\)
\[
(1+z)(1+nz)(1+mnz) = mnz = 0
\]
which with little effort can be solved analytically. Then Green’s function is readily obtained by inserting the solution of the eq.(22)
\[
G(\mathbf{N}(z)) = \frac{z(\mathbf{N}(z)) + 1}{\mathbf{N}(z)} \Rightarrow \rho(\lambda^2) = -\frac{1}{\pi}\text{Im}\mathbf{G}(\lambda + i\epsilon)
\]
This will lead to a rather complicated form of the final function
\[
\rho(\lambda) = \left(\frac{2}{\theta(\lambda^2)}\right)^{1/3} 3^{-1/2} \frac{\pi \lambda}{\xi} \left(2^{-2/3} + \varphi(\lambda^2)\right)
\]
where
\[
\varphi(\lambda^2) = 2 - 3m(1-m) - 3n(1-n) + 
-3mn(m + m - 4) + 2(m^3 + n^3) + 9\lambda^2(1 + m + n),
\]
\[
\theta(\lambda^2) = \varphi(\lambda^2) + 
-\sqrt{\varphi(\lambda^2) - 4(1 + m^2 + n^2 - mn - m - n + 3\lambda^2)^3}.
\]

### 3.3. Example from the data
The last decade has been a witness of an enormous progress in the development of small-scale macroeco-
It’s not too much an overstatement to say, that the statistical analysis of VAR models, Kalman filter models etc. is nowadays complete. The major issue with these models is that they can accurately approximate small number of time series only. On the other hand Central Banks must construct their forecasts in rich data environment [31]. This mismatch between standard macroeconomic models and real world practice has led to unfortunate consequences. Forecasters have had to rely on informal methods to distill information from available data, and their published forecasts reflect considerable judgement in place of formal statistical analysis. Forecasts are impossible to reproduce, and this makes economic forecasting a largely non-scientific activity i.e., formal small-scale models have little effect on day-to-day policy decisions, making these decisions more ad hoc and less predictable than if guided by the kind of empirical analysis that follows from careful statistical modeling. The goal of this research is to use the wide range of economic variables that practical forecasters and macroeconomic policymakers have found useful, and establish a direction that explicitly incorporates information from a large number of macroeconomic variables into formal statistical models. We have focused on two different data sets, namely Polish macroeconomic data and generated set of data, where temporal cross- correlations are introduced by definition. The full data set is the same as it was used in previous section.

3.3.1. Polish macroeconomic data revisited

Poland is an interesting emerging market with unique social and business activity in the process of rapid growth and industrialization. We hope our analysis might be helpful in understanding the factors that helped Poland to survive during the 2008 crisis. The main problem to be solved is to choose the correct variables to include. This is the familiar problem of variable selection in regression analysis. Economic theory is of some help, but usually suggests large categories of variables (money, interest rates, wages, stock prices, etc.) and the choice of a specific subset of variables then becomes an open problem. The analysis began with checking, whether the method described in [13] is relevant for describing the relation between the inflation indexes for Polish macroeconomic indexes and other Polish macroeconomic data published by different government and non-government agencies. A consumer price index (CPI) is a measure estimating the average price of consumer goods and services purchased by households. A consumer price index measures a price change for a constant market basket of goods and services from one period to the next within the same area (city, region, or nation). It is a price index determined by measuring the price of a standard group of goods meant to represent the typical market basket of a typical urban consumer. The percent change in the CPI is a measure estimating inflation. It is commonly viewed as the indicator not only the measure of inflation, but rather the indicates the change of costs of maintenance. The data set represent a wide range of macroeconomic activity and were initially transformed to ensure stationarity and diminish the effects of seasonal components. The same data set we have already analyzed in the first part of the paper and the detailed list of all time series can be obtained from the author upon request. This time, the whole set of 52 time series, observed on a monthly basis between Jan – 2000 and Oct – 2009 (T = 118) was divided into two subsets i.e.,

- We have used monthly $M = 15$ changes of different CPI indicators as our predicted variables (i.e. output sample $Y$)
- The input sample $X$ consisted of $N = 37$ monthly changes of economic indicators (eg. sectoral employment, foreign exchange reserves, PPI’s) as explanatory variables.

The data were standardized and mean adjusted, but following the general idea of [13] the input and output samples’ factors were not selected very carefully, so the data could speak for themselves and system could be able to select the optimal combination of variables.

Fig. 3. Correlation matrices representing generic in-the-sample correlations. The data were mean adjusted and standardized. In a perfect situation, one is expecting that cross-correlations tends to zero, however still nontrivial correlations are present. LEFT: Matrix with 37 input variables $X$. RIGHT: Matrix with 15 input variables $Y$ - components of CPI.

The resulting diagrams (see Fig.3) now demonstrate, that even standardized and converted to stationary time series may represent nontrivial in-the-sample correlations. Short-term economic forecasts build from these type data in consequence may be poor and show no sign of improving over time. The next step involved cleaning internal correlations in each sample. To do it, we have used equation (16). The effective matrices were then diagonalized and two sets of internally uncorrelated data were prepared.

3.3.2. Results for equal-time spectra

From the uncorrelated data we create the rectangular matrix $G$ and diagonalize it to calculate singular eigenvalues. Finally we have used the benchmark calculated in equation (18) to compare the data with the predicted eigenvalue density. For the same data sets we have also created the set of correlated samples i.e., the set, where internal spatial cross-correlations were not a-priori removed (see Fig. 4). Apparently there is enough idiosyn-
cric variation in standard activity measures like the unemployment rate and capacity utilization, that removing noisy components from these might provide a clearer picture of factors affecting inflation. We have excluded from further analysis series responsible for reference NBP bill rate balance of payments, and from the set of explanatory variables ordinary measures of inflation - CPI in food sector, beverages and tobacco ans services.

This approach allows us to directly reproduce temporal cross-correlations.

The lack of symmetry condition endure us to focus only on out-of-the-sample correlations without mixing them with inner ones and to study temporal properties of such matrix. The results show, that there exists some singular eigenvalues, which do not fit the benchmark. Among them, the highest singular eigenvalue \( s_1 = 2.5 \) and the corresponding singular eigenvector, represent standard negative correlation between expenses for electricity and net balance of payments in the energy and positive correlation between CPI in health sector and unemployment. In our approach we can not only observe this relations, but also interpret them in terms of causality. That is, larger unemployment rate causes increase in the CPI. There are other non-trivial relations between eg. CPI in telecommunication sector and foreign exchange reserves. All of these correlations are however well known from textbooks or can be easily explained by means of classical economic theory. When some of the eigenvalues become strongly related, zero modes emerge - clearly the majority (around 80% of all eigenvalues are concentrated close to zero, meaning that there are strong spatial correlations inside X and Y data set. If we are to use the \( MP^2 \) benchmark then it is clear, that empirical spectrum is affected by idiosyncratic components, again confirming, that spatial structure strongly interferes with temporal, and it is crucial to "remove" redundant factors to avoid spurious (confounding) correlations.

### 3.3.3. Solution for lagged spectra

A natural way to examine macroeconomic data is via factor models. In previous section we have assumed that the inflation can be accurately explained by the factor model using relatively small number of latent variables. Pushing the factor model one step further, these latent factors might also explain the predictive relationship between current values of variables and those of the previous month. The next step of our study involved shifting the input and output data set by one observation (one month). The \( Y \) were calculate from \( t = 2, \ldots,118 \) and \( X \)'s for \( (t = 1, \ldots,117) \). We were motivated by the common belief, that it is the "yesterday" shock, that affects "today" change i.e., there is some persistency and long memory within this system. This is the same approach, that underlies the idea of VARMA(\( q_1, q_2 \)) processes [3].

The temporal structure (Fig. 5) manifests itself via the existence of significant non-symmetric relation (represented by one singular eigenvalue, that does not fit the benchmark) between data sets \( X \) and \( Y \), that are shifted by one month. It is easy to notice, that only few factors are responsible for the model's performance.

CPI in telecommunication sector is affected by the largest number of possible explanatory variables (c.f. Table II.). Among them the most unexpected is the correlation with heavy trucks. Two or three factors are useful for some categories of series, but only a single factor is responsible for the predictability of prices in all sectors. Apparently, the first factor is foreign exchange reserves level, and the results say that it is an important predictor of future prices in telecommunication, manufacturing and transport sector. We can say that when forecasting inflation a large model might be a clue, but if we remove redundant factors the inflation can be forecasted by using simple measures of real activity like the unemployment rate, industrial production or capacity utilization. While the first factor is easy to interpret, a complete understanding of the results requires an understanding of other factors as well. Unfortunately, their interpretation and
role in explaining future changes in the consumer prices is an open question.

3.4. Conclusions

We will now recap this illustrative study with few comments:

- In general both input and output data sets may represent highly complex correlation structure strongly interfered by redundant noisy factors. This significant amount of noise need to be carefully eliminated by performing initial decoupling of spatial correlations, so these large matrices become mutually free.

- This is again precisely the case when FRV approach “takes the stage” and reduces the solution to few lines.

- The procedure tested on real data within the case of unshifted variables hasn’t show any significant improvement in comparison to standard factor analysis known in econometric literature for similar data sets [32]. For data lagged by one observation we have however recovered the sea of different non–trivial relations, and it might be interesting to compare these results from a more general perspective of factor models, however no implicitly close approach was found in the literature.

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References